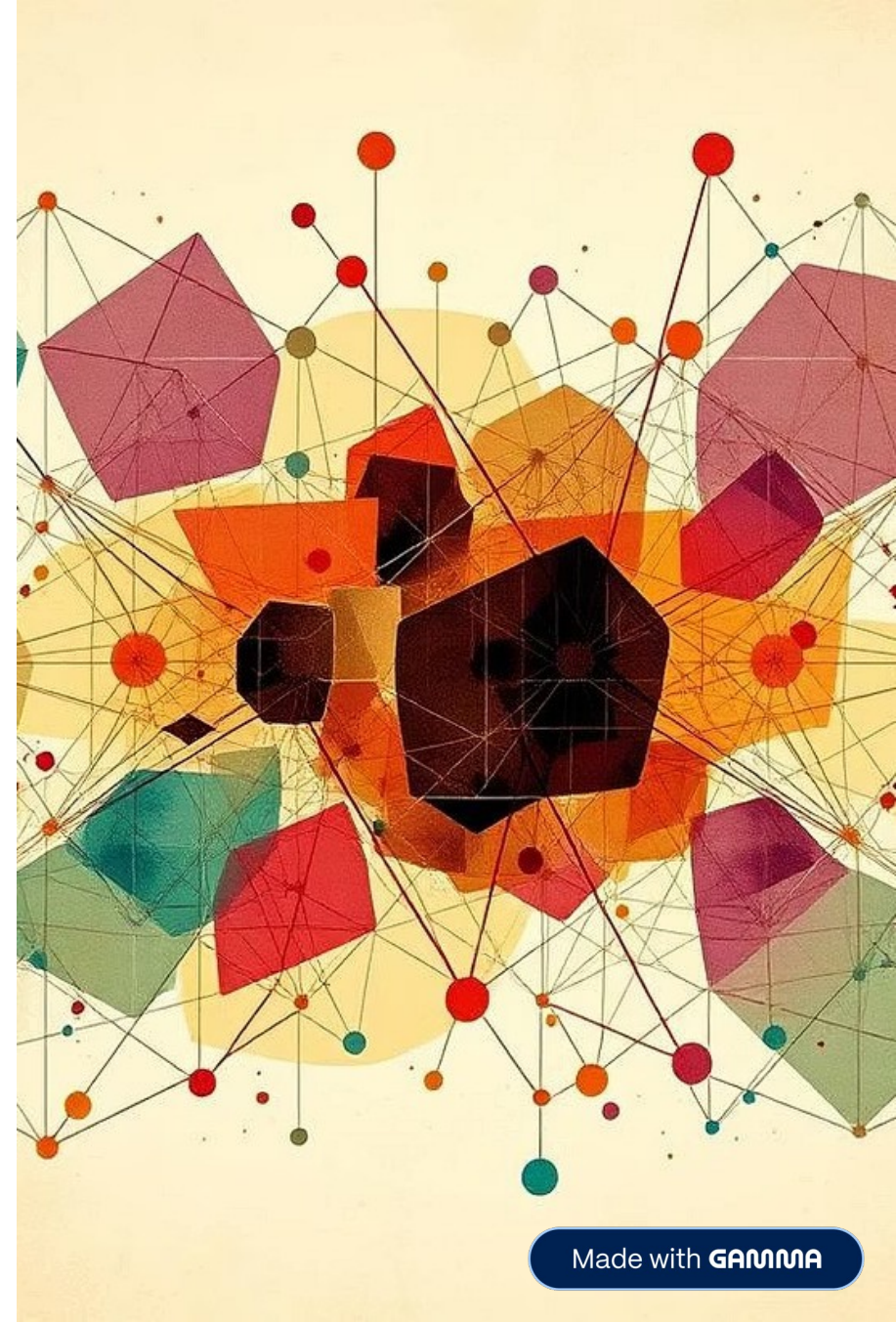


# Introduction Matrices



# Elementary Matrix Operations

## Matrix Addition

Matrices of the same dimensions can be added by summing their corresponding elements. This operation is only defined for matrices with an identical number of rows and columns.

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} + \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} a + e & b + f \\ c + g & d + h \end{bmatrix}$$

## Matrix Subtraction

Similar to addition, matrices of the same dimensions can be subtracted.

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} a - e & b - f \\ c - g & d - h \end{bmatrix}$$

## Properties of Matrix Addition

### Commutative

$$A + B = B + A$$

The order of addition does not affect the result.

### Associative

$$(A + B) + C = A + (B + C)$$

Grouping of matrices does not affect the sum.

# Rank of Matrices



## Definition

Maximum number of linearly independent rows or columns in a matrix.



## How to Find

Row-reduce the matrix to its echelon form, then count the number of non-zero rows.



## Properties

- $\text{rank}(A) \leq \min(\text{rows}, \text{columns})$ .
- Full rank occurs when  $\text{rank}(A) = \min(\text{rows}, \text{columns})$ .



## Example

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \rightarrow \text{rank} = 1$$

(Rows are linearly dependent)

# Determinants of a Square Matrix

## Definition

A determinant is a **scalar value** computed from the elements of a square matrix. It provides important information about the matrix, such as its invertibility.

## 2x2 Formula

For a 2x2 matrix:

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$$

## Key Properties

$$\det(I) = 1, \det(\text{zero matrix}) = 0$$

Swapping rows reverses the sign of the determinant.

$$\det(AB) = \det(A) \det(B)$$

# Inverse of a Square Matrix



## Definition

$A^{-1}$  such that  $AA^{-1} = I$ . Exists if  $\det(A) \neq 0$ .



## Properties

$$(AB)^{-1} = B^{-1}A^{-1}. (A^{-1})^T = (A^T)^{-1}.$$



## Calculation Methods

Adjugate Formula:  $A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$ . Or Row Reduction:  
 $[A|I] \rightarrow [I|A^{-1}]$ .



## Example

For  $A = \begin{bmatrix} 2 & 3 \\ 1 & 4 \end{bmatrix}$ ,  $\det(A) = 5$ , then  $A^{-1} = \frac{1}{5} \begin{bmatrix} 4 & -3 \\ -1 & 2 \end{bmatrix}$ .

# Solution of a System of Linear Equations using **Cramer's Rule**

**Cramer's Rule** is a method to solve a system of linear equations using determinants. It works only when the number of equations equals the number of unknowns and the determinant of the coefficient matrix is **non-zero**.

Consider the system:

$$\begin{aligned}a_1x + b_1y &= c_1 \\ a_2x + b_2y &= c_2\end{aligned}$$

**Step 1: Compute the main determinant (D)**

$$D = \begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} = a_1b_2 - a_2b_1$$

**Step 2: Compute  $D_x$  and  $D_y$**

Replace columns with constants:

$$D_x = \begin{vmatrix} c_1 & b_1 \\ c_2 & b_2 \end{vmatrix}, D_y = \begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix}$$

**Step 3: Find the solution**

$$x = \frac{D_x}{D}, y = \frac{D_y}{D}$$

# Example

$$\begin{aligned}2x+3y&=8 \\ x+2y&=5\end{aligned}$$

**Step 1: Determinant  $D$**

$$D = \begin{vmatrix} 2 & 3 \\ 1 & 2 \end{vmatrix} = (2 \times 2 - 1 \times 3) = 4 - 3 = 1$$

**Step 2: Compute  $D_x, D_y$**

$$D_x = \begin{vmatrix} 8 & 3 \\ 5 & 2 \end{vmatrix} = (8 \times 2 - 5 \times 3) = 16 - 15 = 1$$

$$D_y = \begin{vmatrix} 2 & 8 \\ 1 & 5 \end{vmatrix} = (2 \times 5 - 1 \times 8) = 10 - 8 = 2$$

**Step 3: Final Answer**

$$x = \frac{1}{1} = 1, y = \frac{2}{1} = 2$$

# Eigenvalues and Eigenvectors

## Eigenvector

A **non-zero vector**  $X$  is called an eigenvector of matrix  $A$  if, when multiplied by  $A$ , it only changes by a scalar factor (not direction).

## Eigenvalue

The scalar  $\lambda$  corresponding to that eigenvector is called the eigenvalue.

## Mathematical Definition

$$AX = \lambda X$$

Where:

$A$  = square matrix

$X \neq 0$  = eigenvector

$\lambda$  = eigenvalue

## In Simple Words

**Eigenvector** → direction remains same

**Eigenvalue** → amount of stretching or shrinking

Characteristic equation:  $|A - \lambda I| = 0$

# Example

Let

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

## Step 1: Characteristic equation

$$\begin{aligned} \begin{vmatrix} 2-\lambda & 1 \\ 1 & 2-\lambda \end{vmatrix} &= 0 \\ (2-\lambda)^2 - 1 &= 0 \\ \lambda^2 - 4\lambda + 3 &= 0 \\ (\lambda-3)(\lambda-1) &= 0 \end{aligned}$$

↳ **Eigenvalues:**

$$\lambda_1 = 3, \lambda_2 = 1$$

**For**  $\lambda = 3$

Solve:

$$\begin{aligned} (A-3I)X &= 0 \\ \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} &= 0 \end{aligned}$$

↳ Equation:  $-x + y = 0 \rightarrow x = y$

✓ **Eigenvector:**

$$X = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

# Example \_ contd.

For  $\lambda = 1$

$$(A-I)X = 0$$
$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

↪ Equation:  $x + y = 0 \rightarrow x = -y$

✓ Eigenvector:

$$X = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

- Eigenvectors are **not unique** (any scalar multiple is also valid).
- Used in:
  - Economics (input-output models)
  - Data science (PCA)
  - Differential equations



# Thank You!

We appreciate your attention and hope this presentation provided valuable insights into Set Theory and Matrices.